

Fig. 1

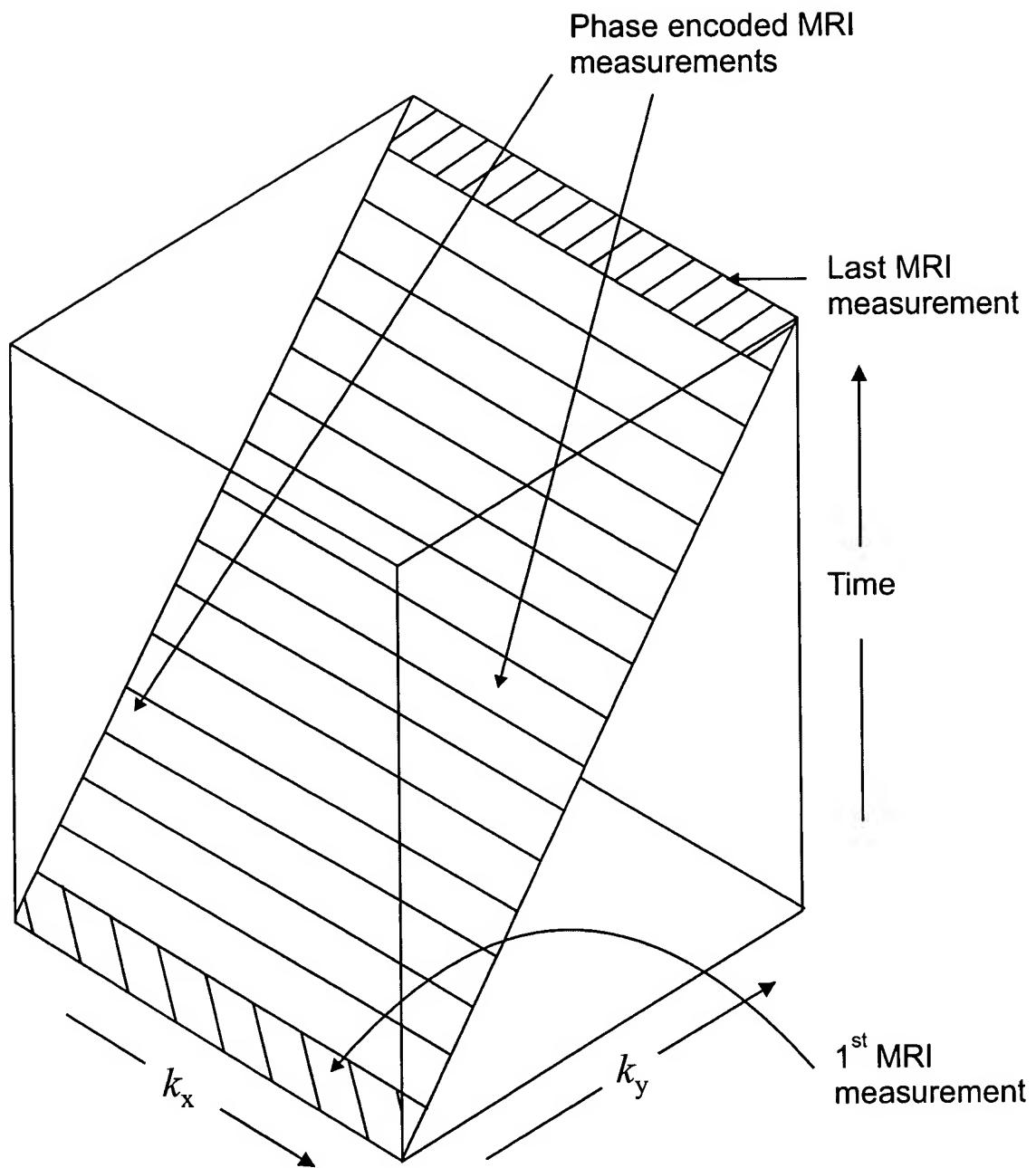


Fig. 2

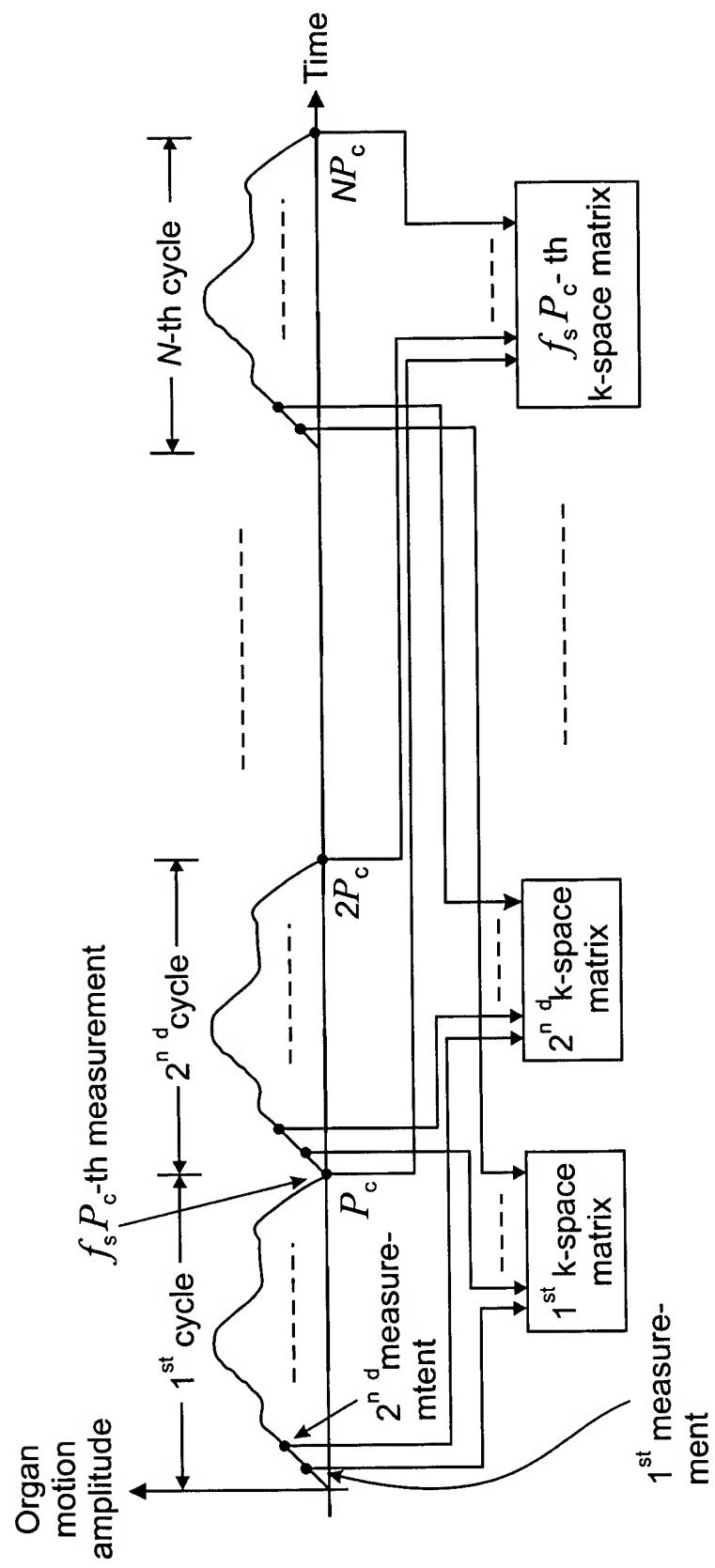


Fig. 3

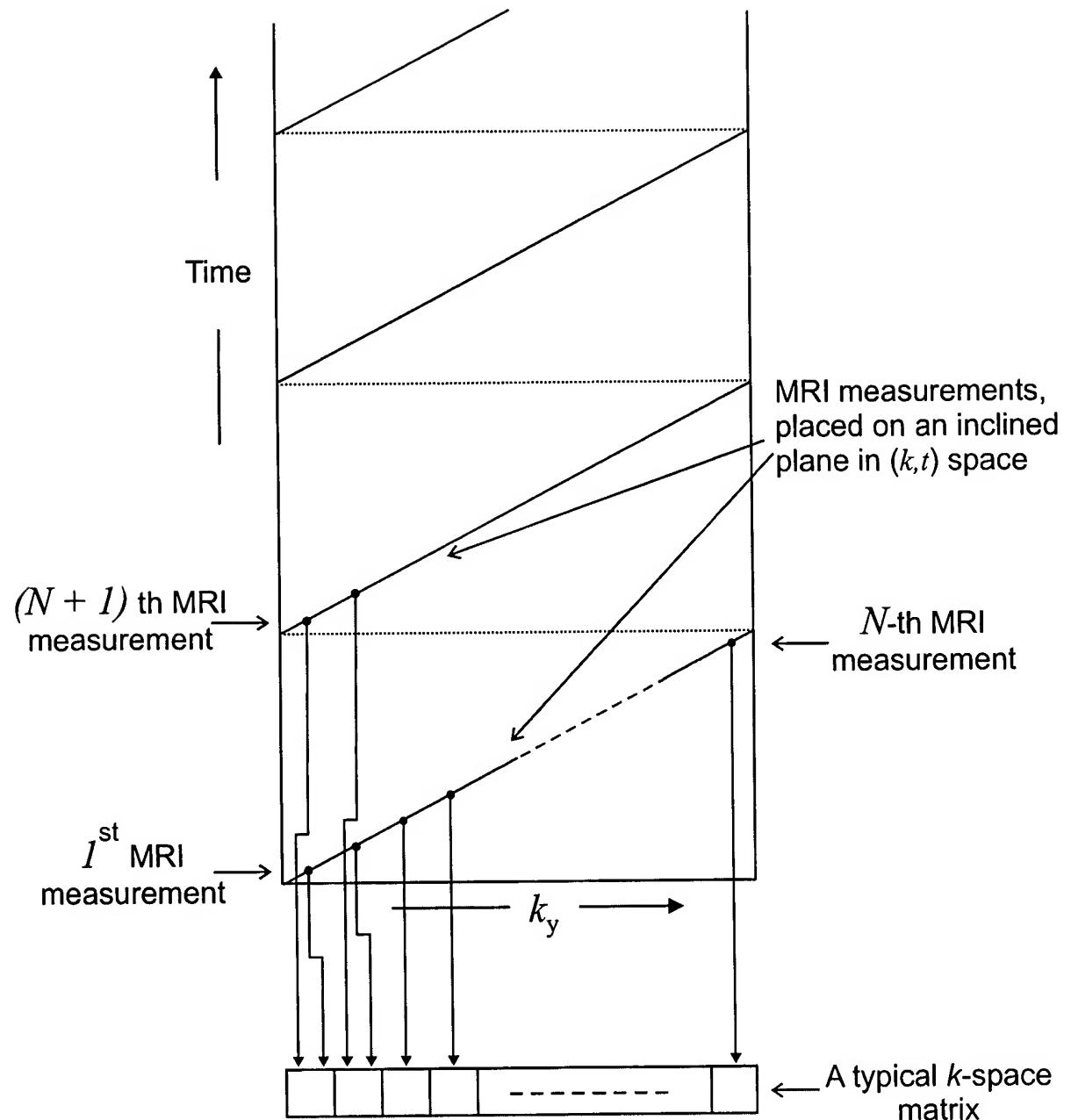


Fig. 4

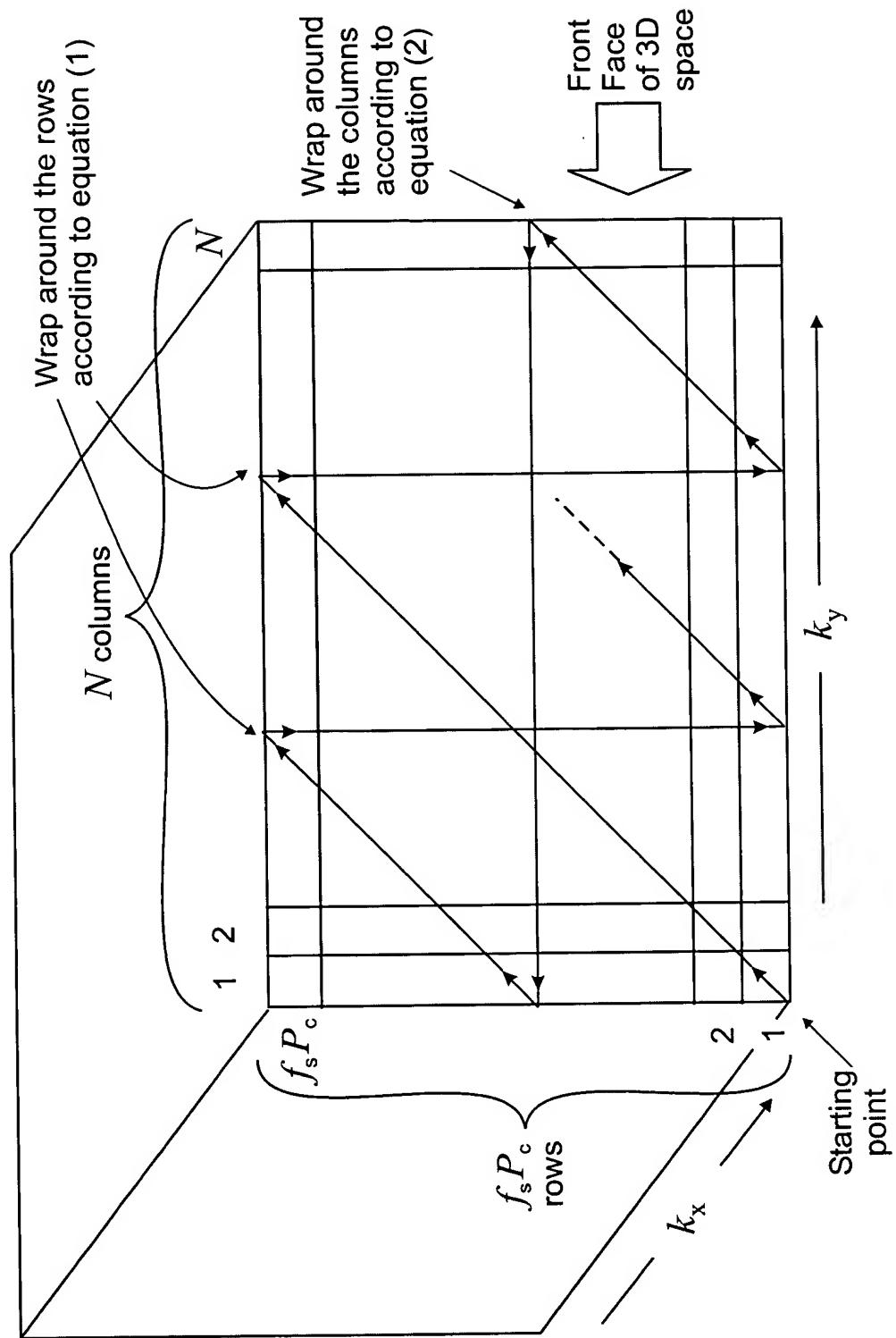


Fig. 5

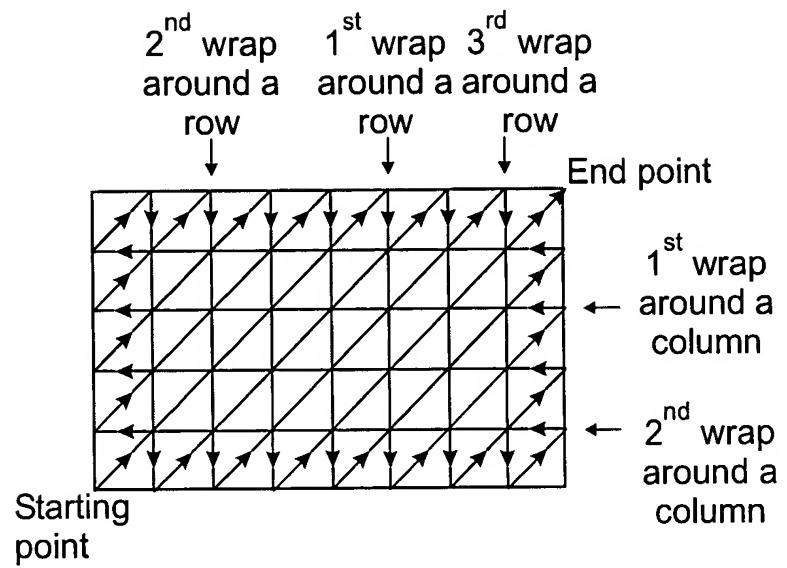


Fig 6a

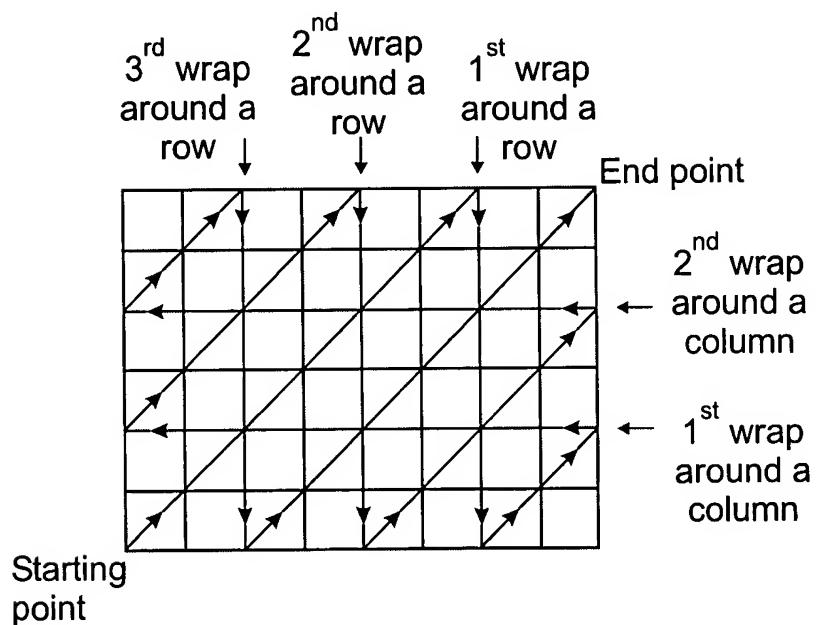


Fig 6b

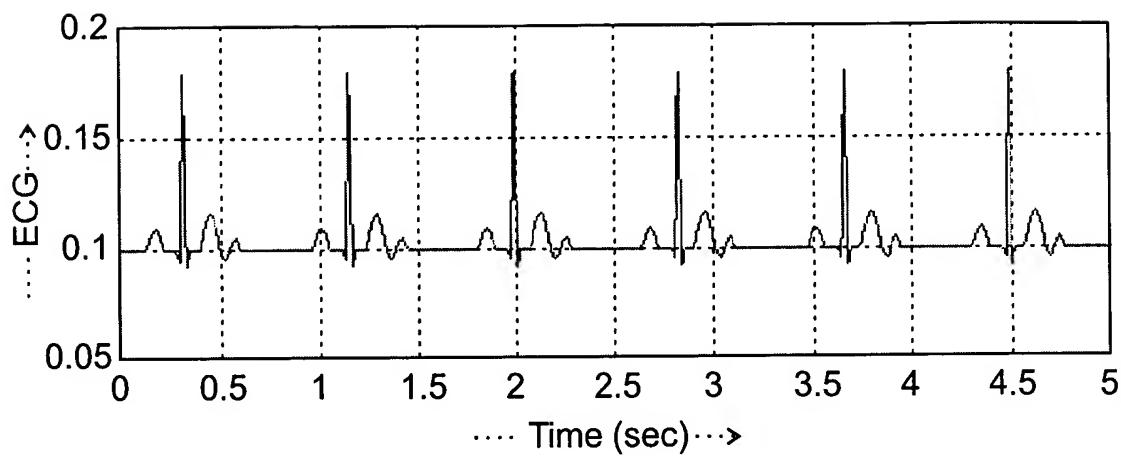


Fig. 7a

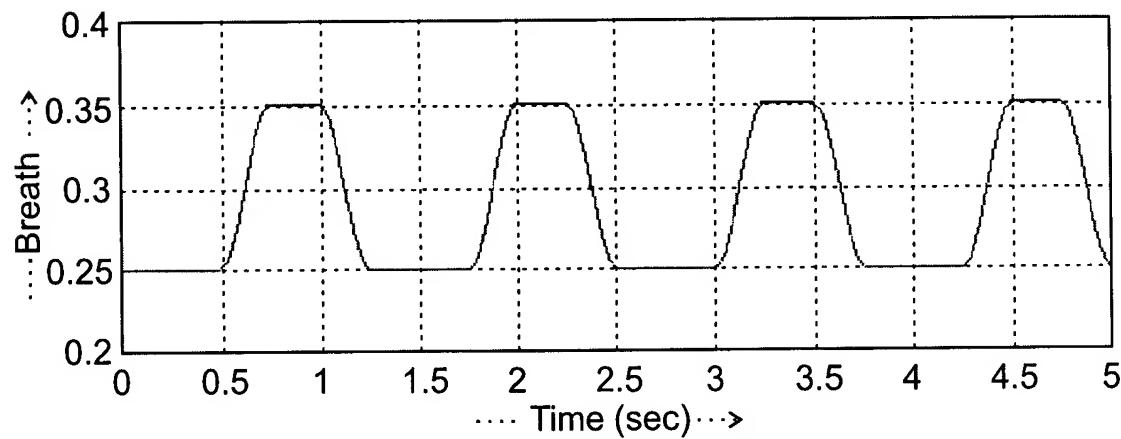


Fig. 7b

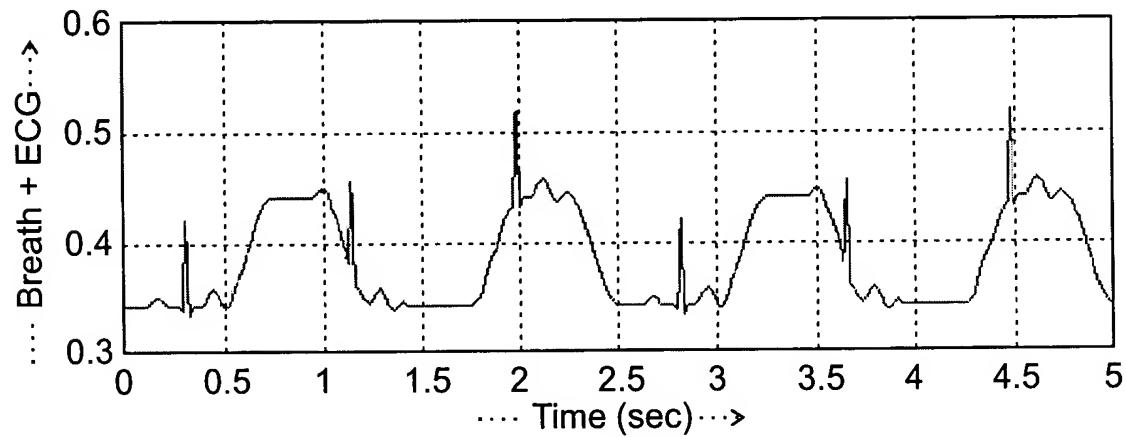


Fig. 7c

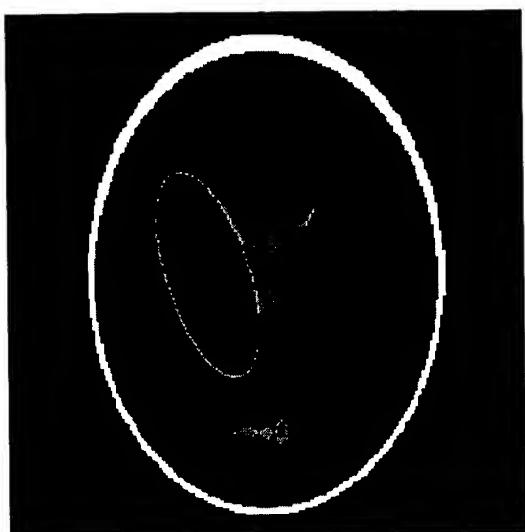


Fig. 8a

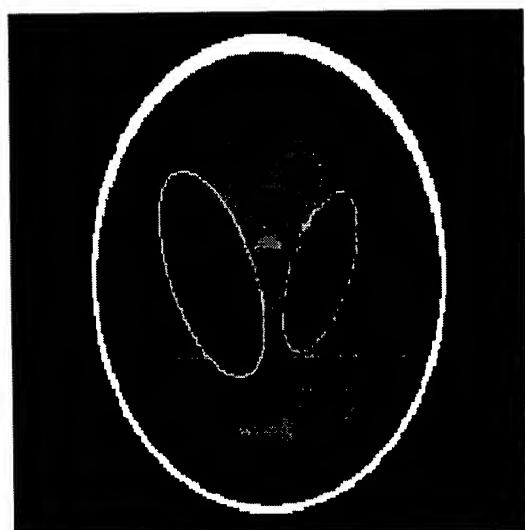


Fig. 8b

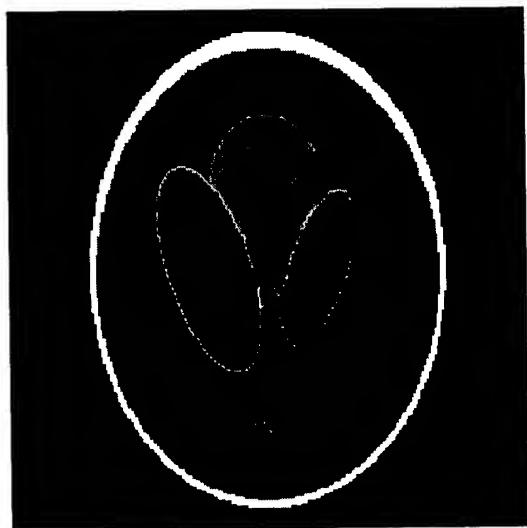


Fig. 8c

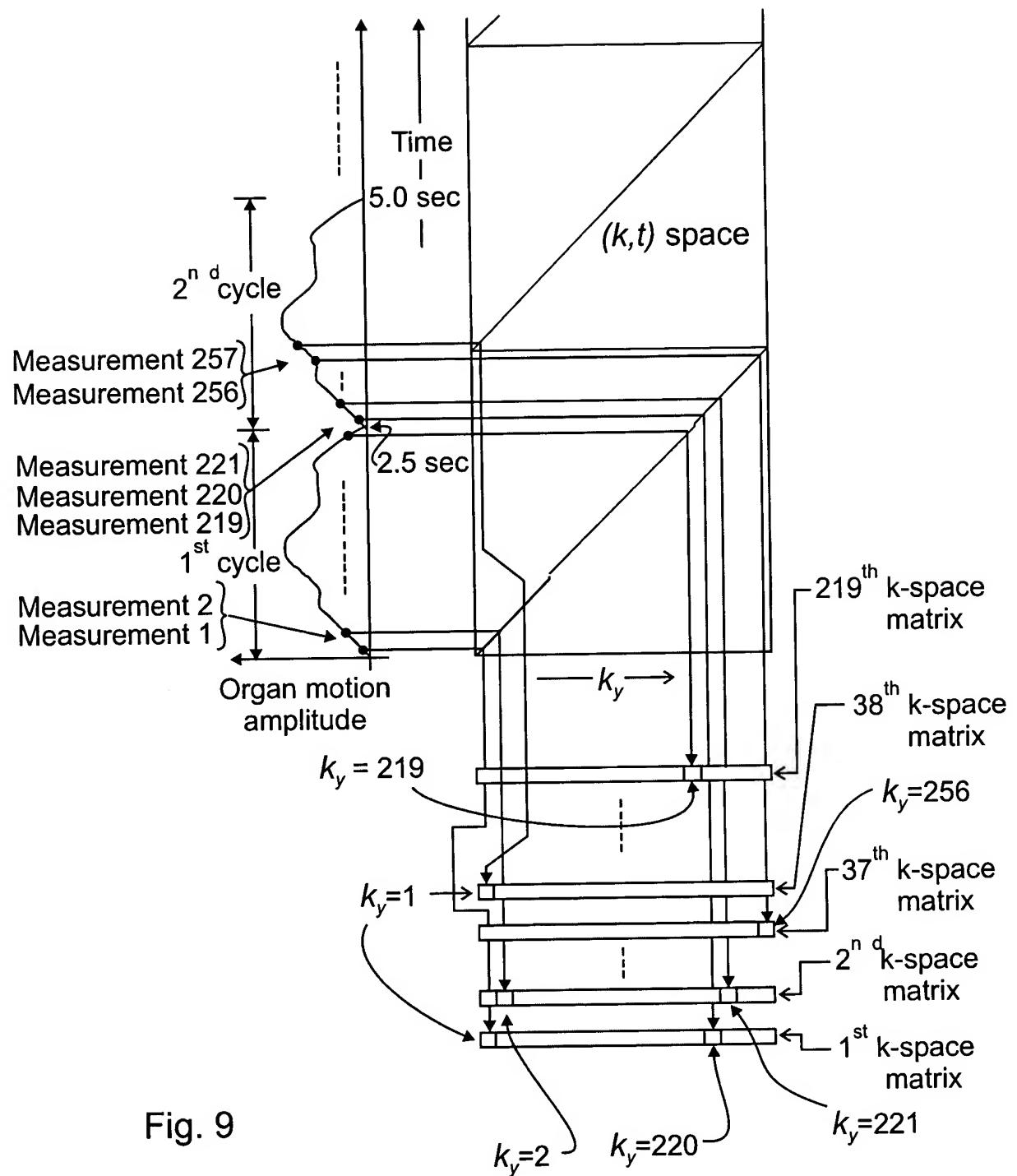


Fig. 9

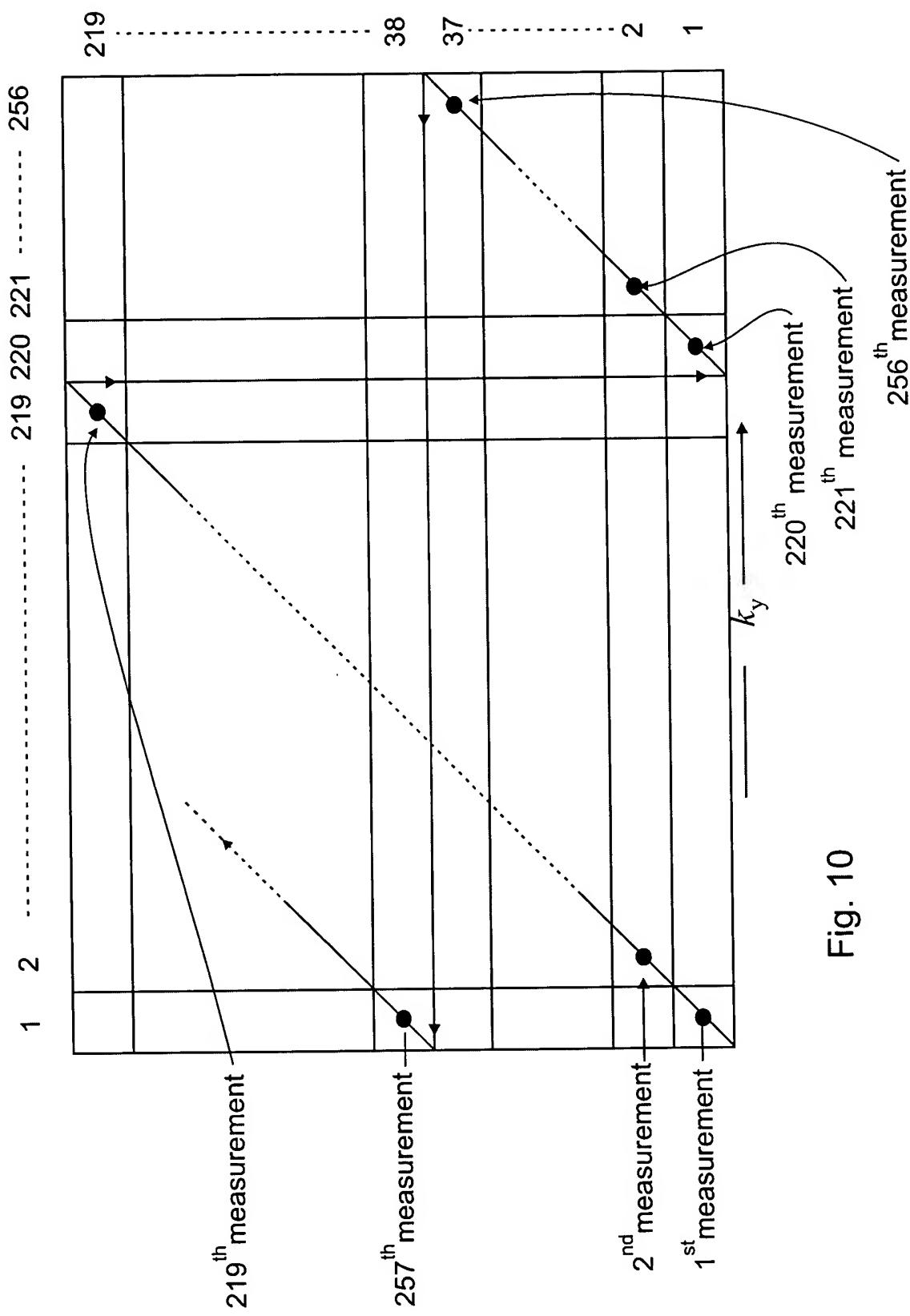


Fig. 10

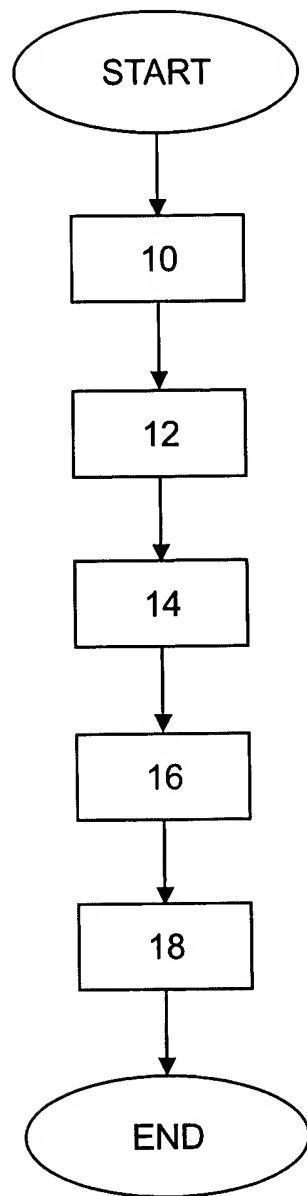


Fig. 11

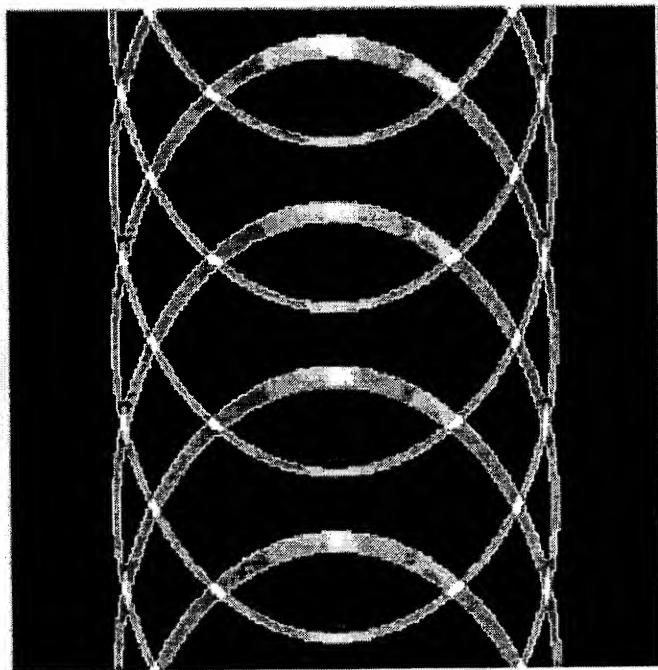


Fig. 12

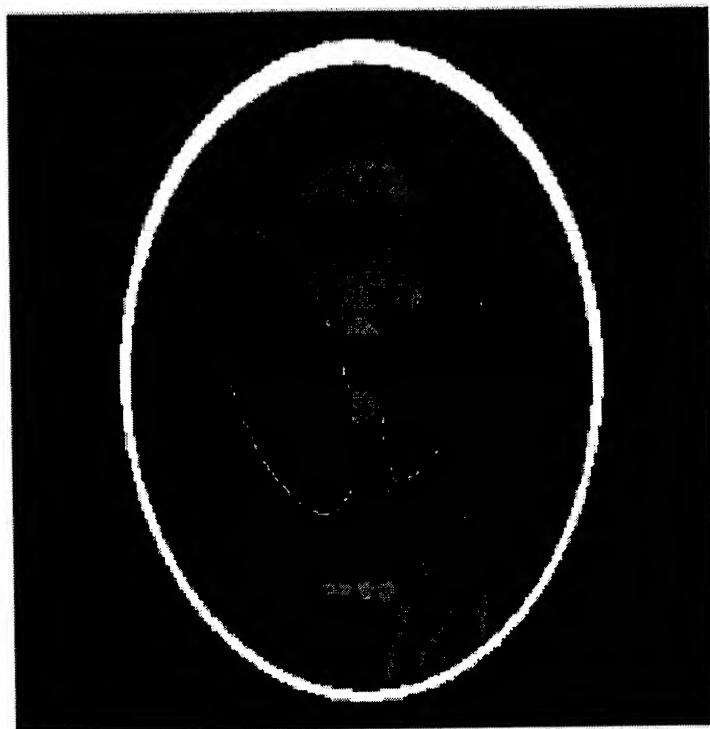


Fig. 13

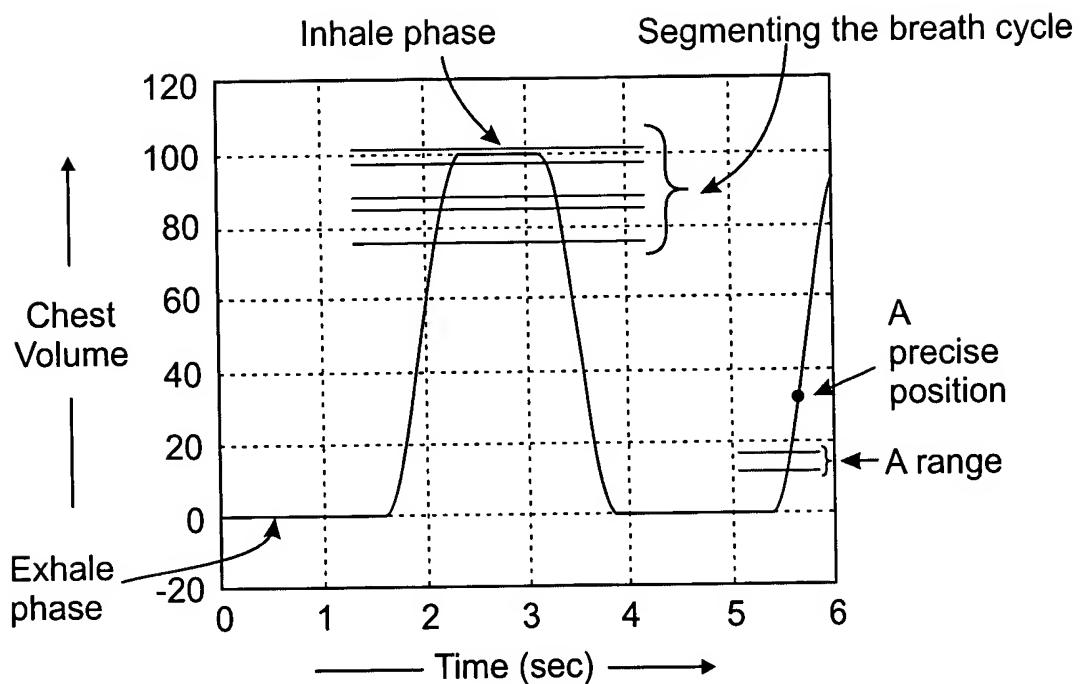


Fig. 14

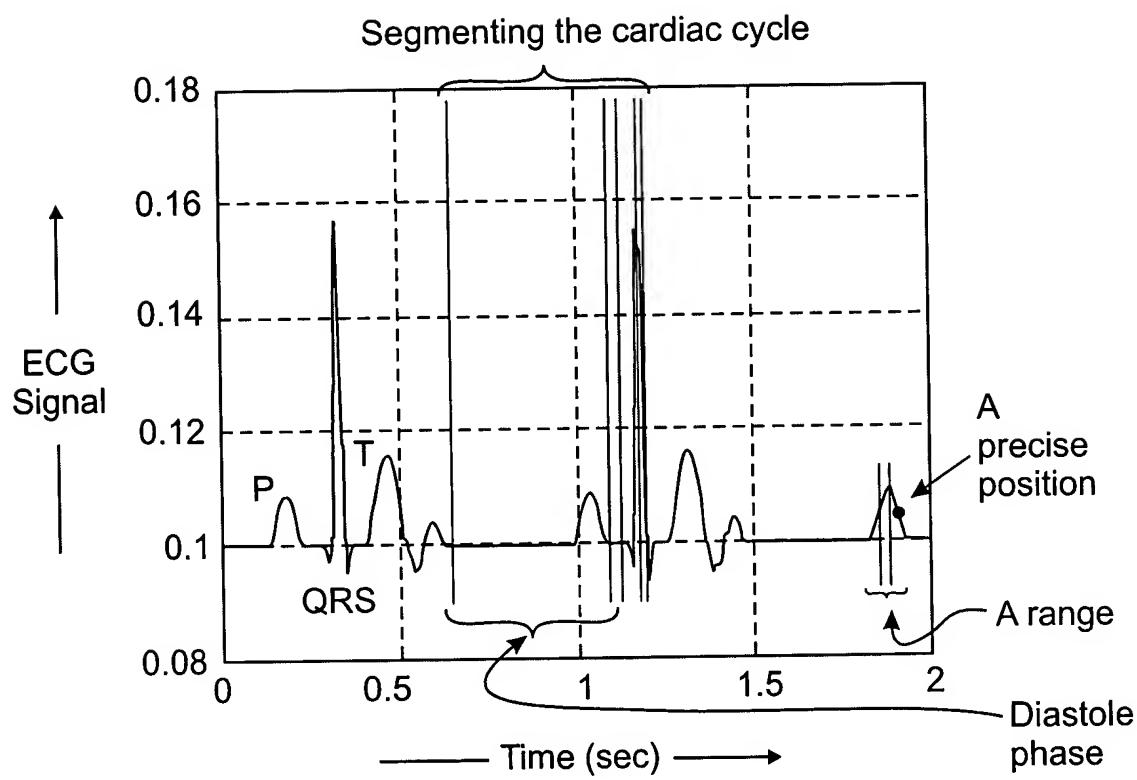


Fig. 15

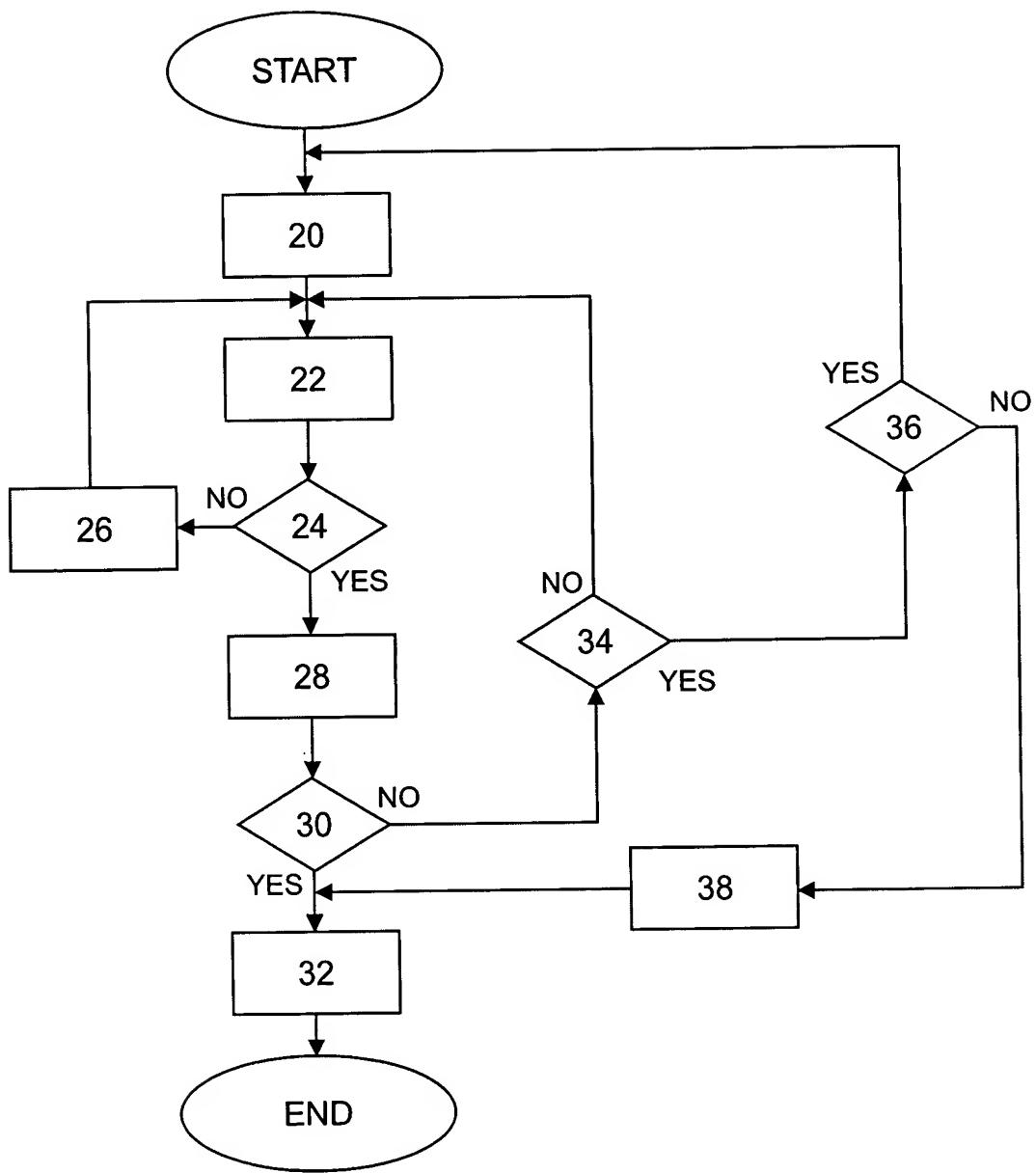


Fig. 16

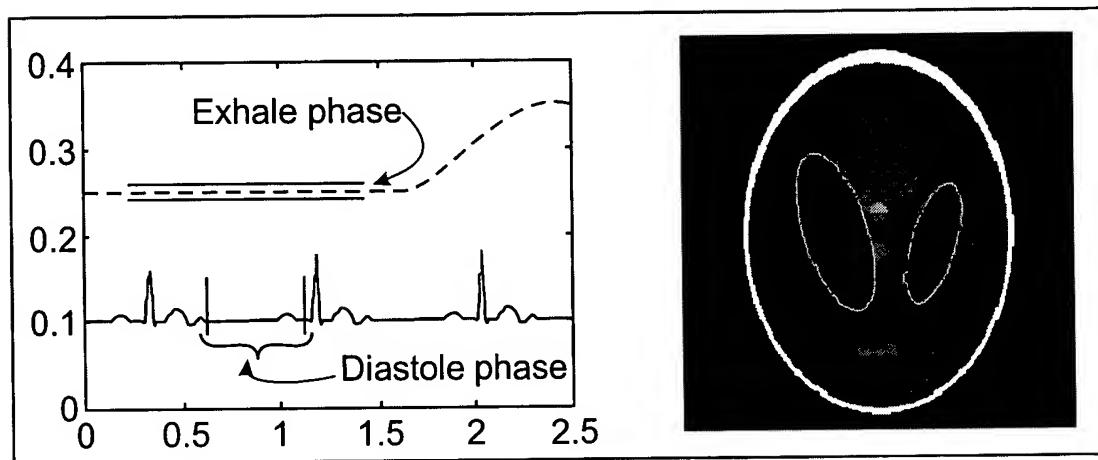


Fig. 17

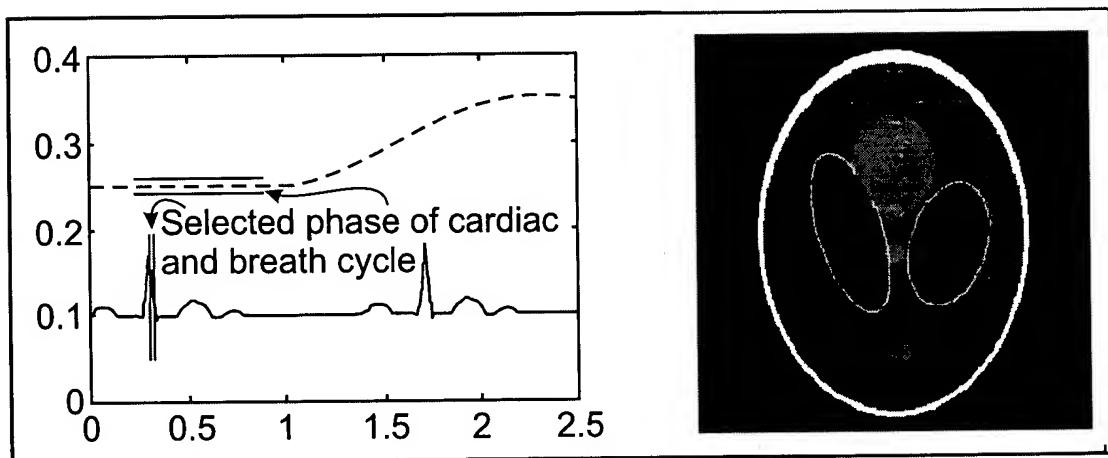


Fig. 18

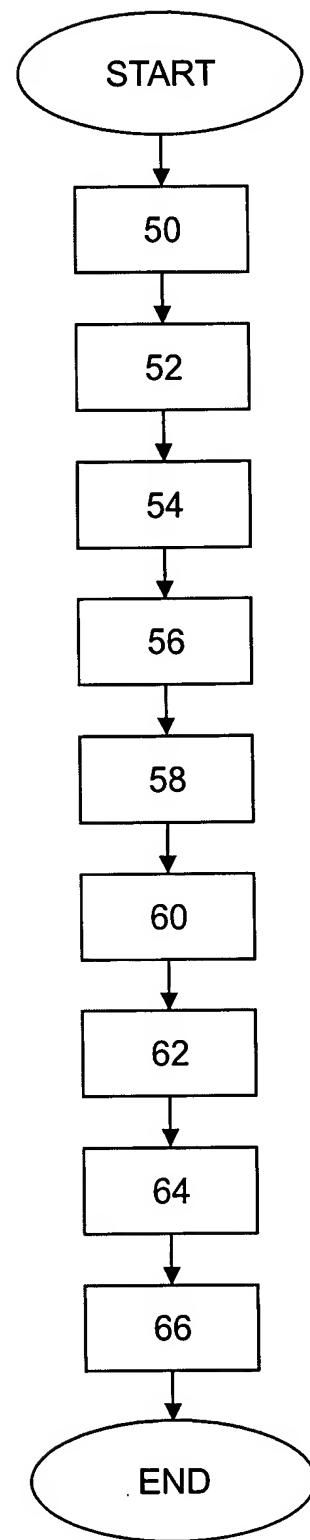


Fig. 19

(a) Initial position

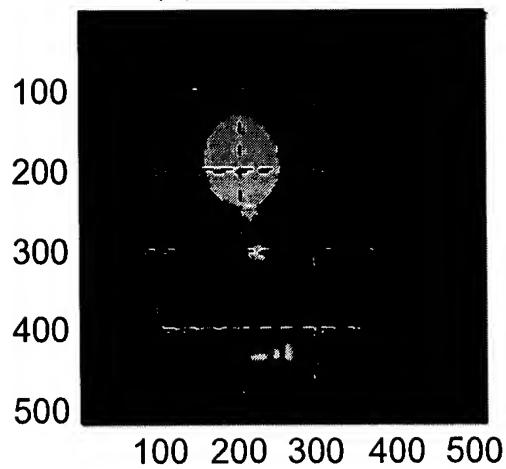


Fig. 20a

(b) Range of motion

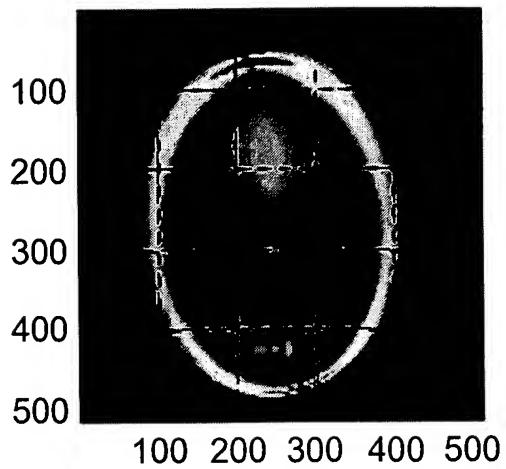


Fig. 20b

(c) Final position

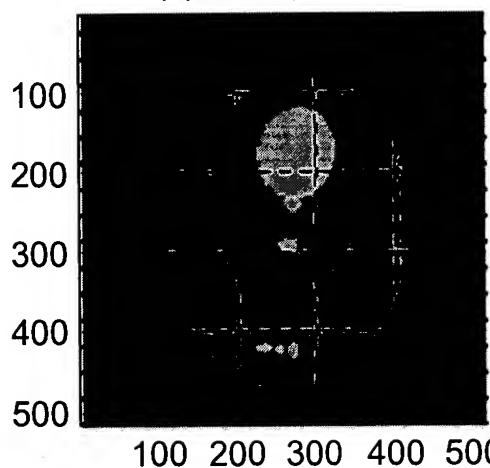
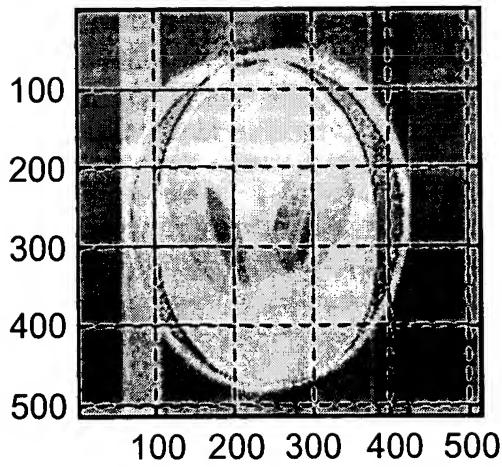


Fig. 20c

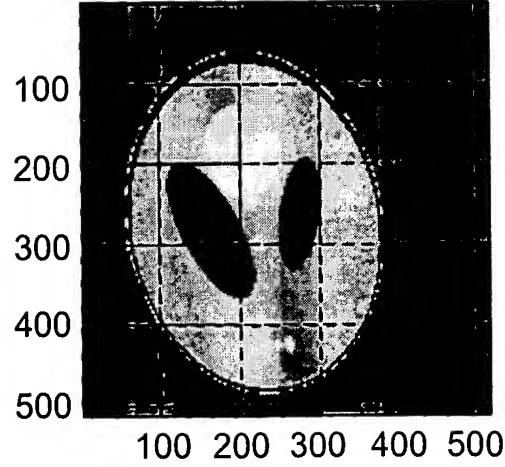
Fig. 20d

Fig. 20e

(d) Uncorrected image



(e) Corrected w.r.t. Initial position



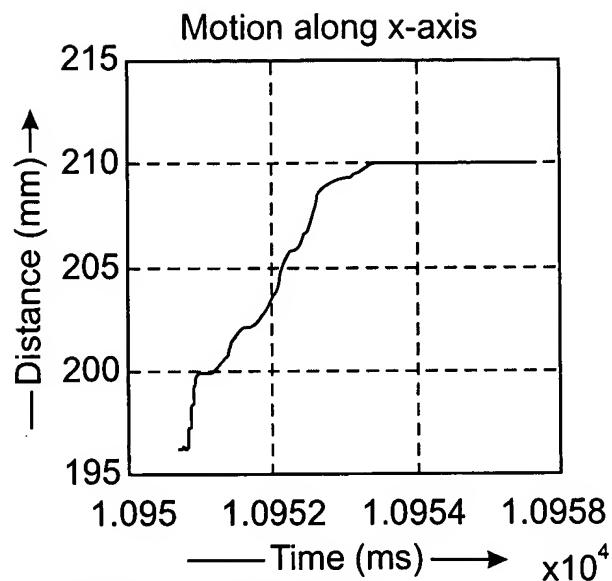


Fig. 21a

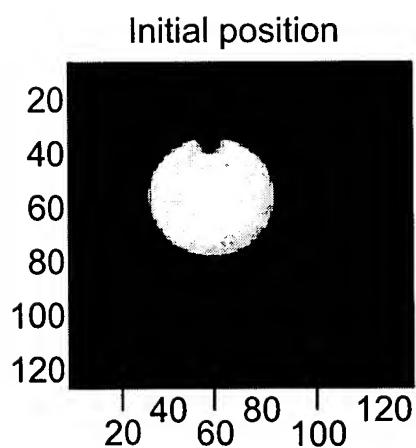


Fig. 21b

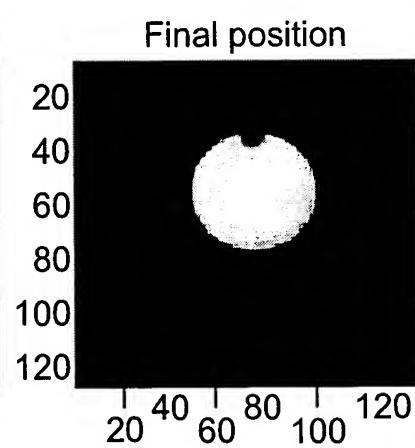


Fig. 21c

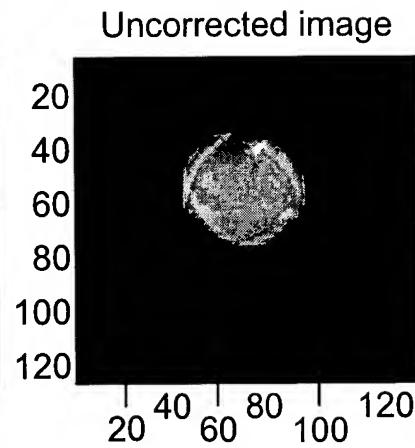


Fig. 21d

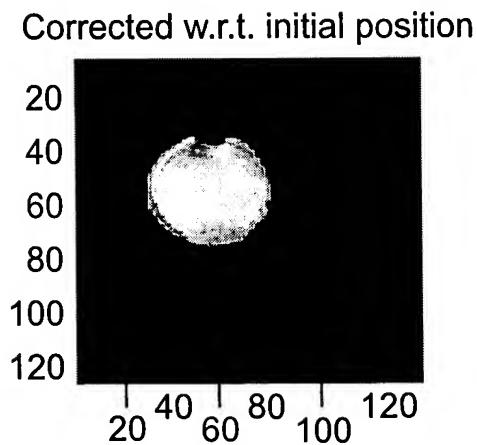


Fig. 21e

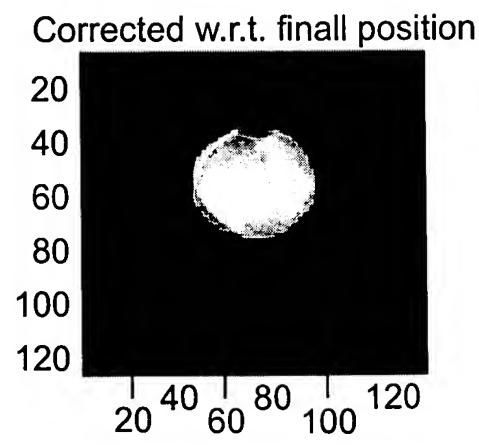


Fig. 21f

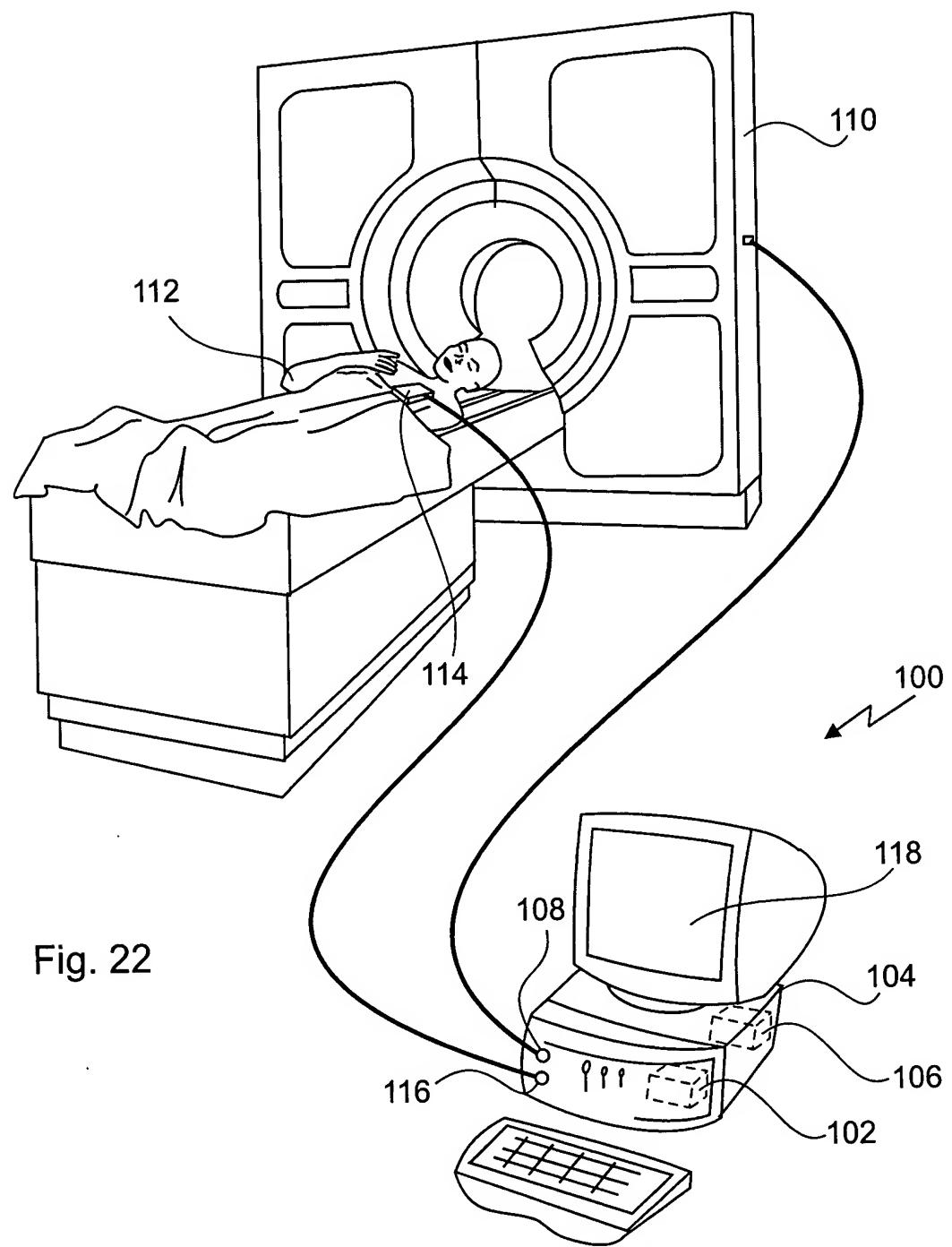


Fig. 22